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(a) Denote the input and output signals as  $x_0(t)$  and  $y_0(t)$ , respectively. Stability of this LTI system ensures that  $y_0(t)$  is bounded. The input signal is  $x_0(t) = e^{0t}$  and thus an eigenfunction of the LTI system with eigenvalue  $H(0)$ . Thus, the output signal will be  $y_0(t) = H(0) x_0(t) = H(0)$ . (b) Denote the output signal as  $y$

Signals, Systems & Inference

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